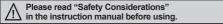
Shaft Type Ø50mm Magnetic Multi-turn Absolute Rotary Encoder

Features

- Higher resistant to vibration and impact by magnetic elements than optical encoder
- Total 23-bit resolution (8,388,608-division) of 10-bit single-turn (1,024-division) and 13-bit multi-turn (8,192-revolution)
- Compact size of Ø50mm
- Parallel data/SSI data transmission type
- Maximizing users convenience with over flow alarm (OVF) function
- Power supply: 12-24VDC ±5%
- Protection structure IP50 (IEC standard)

Applications

Precision machine tool, Fabric machinery, Robot, Parking system





Ordering Information

MGAM50S	8	- 10	13	- B	- F -	- PN	- 24
Series	Shaft diameter	Single-turn	Multi-turn	Output code	Rotation direction	Control output	Power supply
Ø50mm Shaft type	Ø8mm	10-bit (1024 -division)	13-bit (8192 -revolution)	Binary Code	F: Output increases by CW rotation direction at the shaft R: Output increases by CCW rotation direction at the shaft	open collector output S: SSI Line driver output	12-24VDC±5%

■ Specifications

уре		Shaft Type Ø50mm Magnetic Multi-turn Abso	lute Rotary Encoder	
Model		MGAM50S8-1013-B-F-S-24	MGAM50S8-1013-B-F-PN-24	
Resolution Single-turn Multi-turn		1024-division (10-bit)		
		8192-revolution (13-bit)		
Rotation limit	when power off *1	±90°		
	Hysteresis	±0.1°		
	Positioning error ⁸	±1-bit (LSB: Least Significant Bit)		
	Output code	24-bit, Binary code	Binary code	
Output	Control output	SSI (Synchronous Serial Interface) Line driver output [Low] - Sink current: max. 20mA, Residual voltage: max. 0.5VDC== [High] - Sink current: max20mA, Output voltage: min. 2.5VDC==	Parallel NPN open collector output Sink current: max. 20mA, Residual voltage: max. 1VDC==	
<u> </u>	Output signal	Single-turn data, multi-turn count, over flow aları	m (OVF) ^{×3}	
Cat	Output logic	_	Negative logic output	
specification	Response time (rise, fall)	_	Max. 1μs (cable: 2m, I sink = 20mA)	
Multi-turn	Input level	0-1VDC===		
Multi-turn count rese	Input logic	Low Active, Open for common use		
<u>o</u> input [≋] ⁴	Input time	Over 100ms		
SSI clock	Input level	5VDC== ±5%		
input	Input frequency	100kHz to 1MHz		
Max. resp	onse frequency	<u> </u>	30kHz	
Power sup	pply	12-24VDC ±5% (ripple P-P: max. 5%)		
Current co	onsumption	Max. 150mA (disconnection of the load)	Max. 100mA (disconnection of the load)	
Insulation	resistance	Over $100M\Omega$ (at $500VDC$ megger between all terminals and case)		
Dielectric	strength	750VAC 50/60Hz for 1 minute (between all terminals and case)		
Connectio	n	Axial cable type (cable gland)		

X2: When turning ON/OFF the unit, there may be ±1-bit (LSB) error at present position by hysteresis.

X3: OVF alarm is ON when multi-turn count is out of counting range (0 to 8191 revolutions).

^{¾4: Multi-turn count shall be initialized as 「0 revolution」 when multi-turn count reset is input.}

Absolute \$50mm Magnetic Multi-turn Shaft Type

Specifications

Туре		Shaft Type Ø50mm Magnetic Multi-turn Absolute Rotary Encoder			
Model		MGAM50S8-1013-B-F-S-24	MGAM50S8-1013-B-F-PN-24		
	Starting torque	Max. 70gf⋅cm (0.0069N⋅m)			
Maahaniaal	Moment of inertia	Max. 80g·cm² (8×10 ⁻⁶ kg·m²)			
Mechanical specification	Shaft loading	Radial: max. 10kgf, Thrust: max. 2.5kgf			
Max. allowable revolution*5		3,000rpm			
Vibration		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours			
Shock		Approx. max. 50G			
	Ambient temp.	-10 to 70°C, storage: -25 to 85°C			
Environment	Ambient humid.	35 to 85%RH, storage: 35 to 90%RH			
Protection structure		IP50 (IEC standard)			
Cable		Ø6mm, 10-wire, 2m, Shield cable (AWG 28, core diameter: 0.08mm, number of cores: 19, insulator out diameter: Ø0.8mm)	Ø6mm, 17-wire×2, 2m, Shield cable (AWG 28, core diameter: 0.08mm, number of cores: 17, insulator out diameter: Ø0.8mm)		
Accessories		Bracket, coupling			
Approval		C€			
Weight ^{×6}		Approx. 391g (approx. 261g)	Approx. 523g (approx. 393g)		

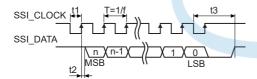
%5: In case of Parallel type model, Make sure that Max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

[Max. response revolution (rpm) = $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$]

%6: The weight includes packaging. The weight in parenthesis is for unit only.

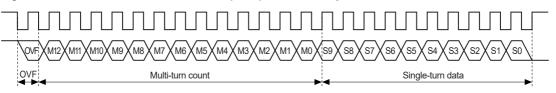
XEnvironment resistance is rated at no freezing or condensation.

■ Synchronous Serial Interface (SSI) Output Timing Diagram



Clock Frequency f	100kHz to 1MHz	
т	T: 1 to 10μs	
	0.5μs < t1 < 5μs	
Time lag t2	t2 < 0.3μs	
Monoflop Time t3	15μs < t3 < 30μs	

■ Synchronous Serial Interface (SSI) Data Output



Clock input bit	Data output name	Data output bit	Clock input bit	Data output name	Data output bit
1	Over flow alarm bit	0-bit	15		9-bit (MSB)
2		12-bit (MSB)	16	-Single-turn data	8-bit
3		11-bit	17		7-bit
4		10-bit	18		6-bit
5		9-bit	19		5-bit
6	Multi-turn count	8-bit	20		4-bit
7		7-bit	21		3-bit
8		6-bit	22		2-bit
9		5-bit	23		1-bit
10		4-bit	24		0-bit (LSB)
11		3-bit			
12		2-bit			
13		1-bit			
14		0-bit (LSB)			

CONTROLLERS

SENSORS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

> Proximity Sensors

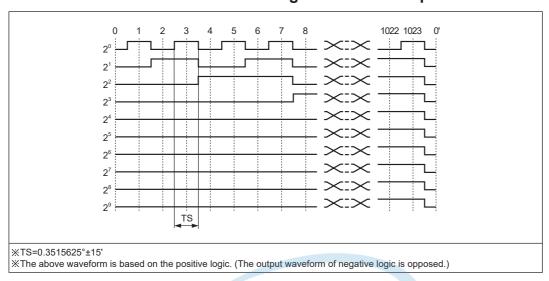
(G) Pressure Sensors

(H) Rotary Encoders

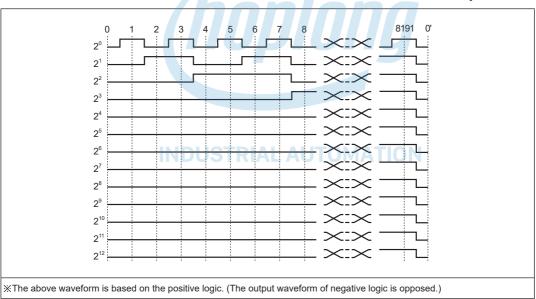
(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

MGAM50S CẬNG TY CỔ PHẦN CÔNG NGHỆ HỢP LONG

■ Parallel Interface 1024-division Single-turn Data Output Waveform

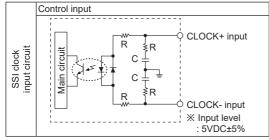


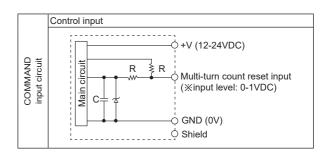
■ Parallel Interface 8192-revolution Multi-turn Count Data Output Waveform



■ Control Output I/O Circuit

O SSI Line driver output type



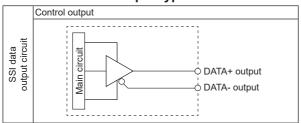


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Absolute \$50mm Magnetic Multi-turn Shaft Type

Control Output I/O Circuit

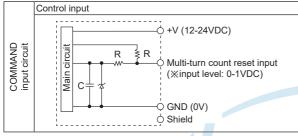
SSI Line driver output type

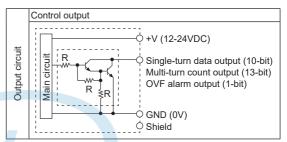


SENSORS CONTROLLERS MOTION DEVICES

SOFTWARE

Parallel NPN open collector output type





※Each bit of output has the same circuit.

*Please be aware of the fact that overload and short circuit may cause circuit break.

Connections

SSI Line driver output type

Cable	Cable					
Cable color	Description		Cable color	Description		
Brown		CLOCK+	Green		Multi-turn count reset	
Red	SSI	CLOCK-	Blue	COMMAND	N·C	
Orange		DATA+	Purple		N·C	
Yellow		DATA-	Gray	1ATION	N·C	
White	+V (12-24VDC)		Shield	Signal shield cable (F.G.)		
Black	GND (0V)		<u> </u>			

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

Vision Sensors

Proximity Sensors

Pressure Sensors

(H) Rotary Encode

Connectors/ Connector Cables/ Sensor Distribution

Boxes/ Sockets

O Parallel NPN open collector output type

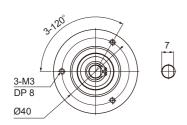
Multi-turn count cable (sheath color: black)					
Cable color	Description				
Brown		2°			
Red		2 ⁰ 2 ¹			
Orange		$ 2^2 $			
Yellow		2 ³			
Green		24			
Blue	Multi-turn	2 ⁵			
Purple	-count	2 ⁶			
Gray	Count	2 ⁷			
Pink		2 ⁸			
Clear		2 ⁹			
Light brown		2 ¹⁰			
Light yellow		2 ¹¹			
Light green		2 ¹²			
Light blue	OVF	·-			
Light purple	Multi-turn count reset				
White	N.C.				
Black	N.C.				
Shield	Signal shield cable (F.G.)				

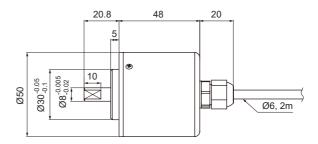
Single-turn data cable (sheath color: gray)					
Description					
	2 ⁰				
1	2 ¹				
1	2 ²				
1	2 ³				
Single-turn	2 ⁴				
data	2 ⁵				
1	2 ⁶				
1	2 ⁷				
	2 ⁸				
	2 ⁹				
N.C.					
+V (12-24VDC)					
GND (0V)					
Signal shield cable (F.G	5.)				
	Single-turn data N.C. N.C. N.C. N.C. N.C. N.C. S.C. N.C. N				

Unused wires must be insulated.
 Do the wiring properly.
 Encoder metal case and shield cable must be grounded (F.G.).
 Please use caution to avoid short circuit when connecting output cables because I/O circuit uses the dedicated driver IC.
 Do not apply tensile strength over 30N to the cable.

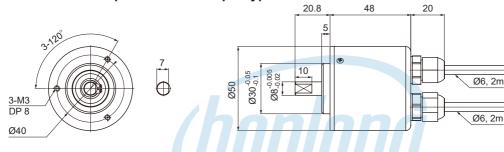
Dimensions (unit: mm)

O SSI Line driver output type





O Parallel NPN open collector output type

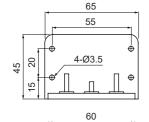


O Bracket

3-Ø3.5

Ø30.8

Ø40

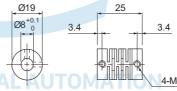


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- Parallel misalignment: max. 0.25mm • Angular misalignment: max. 5°
- End-play: max. 0.5mm
- *Do not load overweight on the shaft.
- *Do not put strong impact when insert a coupling into shaft. Failure to follow this instruction may result in product damage.
- *Fix the unit or a coupling by a wrench under 0.15N·m of torque.
- XWhen you install this unit, if eccentricity and deflection angle are larger, it may shorten the life cycle of this unit.

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- XFor parallel misalignment, angular misalignment, end-play terms, refer to the "Glossary" section of Technical Description.
- XFor flexible coupling (ERB series) information, refer to the ERB series section

Functions

Multi-turn count reset

Multi-turn data will be reset as ¹0 revolution when multi-turn count reset cable (light purple) is inputted 0 to 1V (over 100ms).

Over flow alarm (OVF)

It is an alarm function when multi-turn count is out of rotation ranges (0 to 8191 revolutions).

Over flow alarm is also reset with multi-turn count value when multi-turn count reset signal is inputted.