Industrial PC Platform NY-series IPC Machine Controller

CSM_NY5__-1_DS_E_3_7

The future will be IT driven, we make you part of it

Our IPC Machine Controller combines proven machine automation with the freedom to use PC technology: working together but independently. So you can leverage Big Data, NUI and IoT to explore manufacturing innovation with no compromise on traditional PLC reliability and robustness. It makes engineers unstoppable and machines innovative yet reliable.





NY512

NY532

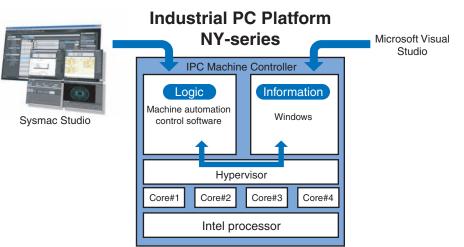
Features

Standard models

- OS independency allows controller to continue to control if a Windows OS crashes
- Primary task period 500 μ s/24 axes
- Retain/non-retain variables 4 MB/64 MB
- 16 to 64 axes
- 192 EtherCAT slaves
- Secure boot and recovery methods
- Powerful 4th-generation CPU technology for optimum performance
- No internal cables in the PC part eliminates faults, maximizes uptime
- Unique simplified thermal design to cut downtime
- Two Gbps Ethernet, one EtherCAT, one DVI, one UPS I/O connector
- Two USB2.0 and two USB3.0 for fast data-transmission

NC integrated models

- Integrate NY-series IPC Machine Controller with Numerical Control (NC) functions.
- Realize high-accuracy synchronization motion control (MC) and numerical control (NC) functions by ONE controller.
- Realize the collaboration of machining process and other processes (loader/unloader, press, assembly).
- Support G codes for numerical control.



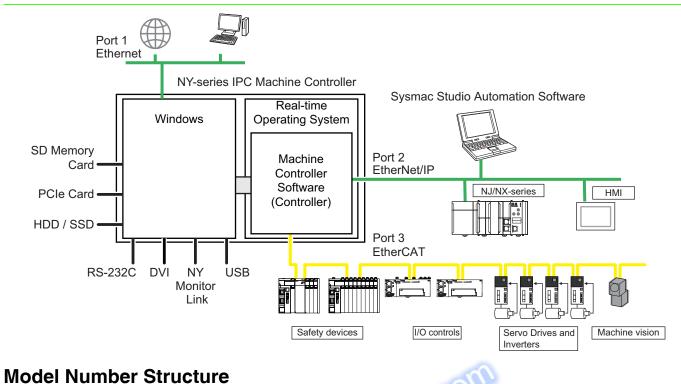
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System Configuration



The purpose of this model number structure is to provide understanding of the meaning of specifications from the model number. Models are not available for all combinations of code numbers.

<u>IY</u>					
1	2 3 4 5	6 7 8 Description	9 10 11 12 13 14 15 16 17 Option	Standard model	NC Integrated mode
1	Series name	NY	NY-series Industrial PC Platform	Yes	Yes
2	Controller specifications	5	Large scale, high speed and high precision control application for up to 64 axes.	Yes	Yes
•		1	Industrial Box PC	Yes	No
3	Model type	3	Industrial Panel PC	Yes	Yes
4	Sequential number	2 or more		Yes	Yes
-		1	Standard	Yes	No
5	Function module	5	Numerical Control (NC)	No	Yes
		3	16 axes	Yes	No
6	Number of axes for	4	32 axes	Yes	Yes
	motion control	5	64 axes	Yes	No
7	Additional function software module	0	-	Yes	Yes
8	Reserved	0	-	Yes	Yes
9	Expansion slots	1	1 PCle slots	Yes	Yes
4.0	10 Frame type	1	Aluminum frame, black, and projected capacitive touch type	Yes	Yes
10		Х	No display (Industrial Box PC)	Yes	No
		1	12.1 inch model	Yes	Yes
11	Display size	2	15.4 inch model	Yes	Yes
		Х	No display (Industrial Box PC)	Yes	No
10	00	1	Windows Embedded Standard 7 - 32 bit *1	No	No
12	OS	2	Windows Embedded Standard 7 - 64 bit	Yes	Yes
13	Processor	1	Intel [®] Core [™] i7-4700EQ 4th generation CPU with Fan Unit for active cooling	Yes	Yes
14	Main memory	3	8 GB, non-ECC	Yes	Yes
		8	32 GB, SSD SLC	Yes	No
	0.	9	64 GB, SSD SLC	Yes	Yes
15	Storage	С	320 GB, HDD	Yes	No
		К	128 GB, SSD MLC	Yes	Yes
		1	RS-232C	Yes	Yes
16	Optional interface	2	DVI-D	Yes	No
		6	NY Monitor Link	Yes	No
		0	OMRON	Yes	Yes
17	Logo	2	Customized logo *2	Yes	Yes
		Х	No display (Industrial Box PC)	Yes	No

*1. For the 32 bit version, consult your OMRON sales representative. (NY50-1)

***2.** Customization only available in Europe.

Ordering Information

NY-series IPC Machine Controller

Recommended models

The industrial PC Platform has extended configuration possibilities to meet your requirements, below an overview of the most used and recommended models. Selecting one of the models below will bring the benefit of faster delivery times.

In case your preferred model is not listed below, please contact your Omron representative to discuss the possibilities.

			Spec	ifications			
Product name	Operating system	CPU type	Number of motion axes	RAM memory (non-ECC type)	Storage size	Interface option	Model
			64		64 GB SSD type (SLC)		NY512-1500-1XX21391X
			04	8 GB	320 GB HDD type	RS-232C	NY512-1500-1XX213C1X
Industrial	Windows Embedded Standard 7 - 64bit	Intel [®] Core™ i7- 4700EQ 32	32 8		64 GB SSD type (SLC)		NY512-1400-1XX21391X
Box PC					320 GB HDD type		NY512-1400-1XX213C1X
			16		64 GB SSD type (SLC)		NY512-1300-1XX21391X
					320 GB HDD type		NY512-1300-1XX213C1X
		39		8 GB	64 GB SSD type (SLC)		NY532-1500-111213910
			64		320 GB HDD type		NY532-1500-111213C10
Industrial	Windows Embedded		32		64 GB SSD type (SLC)	RS-232C	NY532-1400-111213910
Panel PC	Standard 7 - 64bit				320 GB HDD type	RS-2320	NY532-1400-111213C10
			10	1	64 GB SSD type (SLC)	1	NY532-1300-111213910
		16		320 GB HDD type	1	NY532-1300-111213C10	

NY-series IPC Machine Controller NC Integrated Controller

	Specifications							
Product name	Operating system	CPU type	Number of motion axes	NC Function	RAM memory (non-ECC type)	Storage size	Interface option	Model
Industrial Panel PC	Windows Embedded Standard 7 64 bit	Intel [®] Core™ i7- 4700EQ	32 *1	Enable *2	8 GB	64 GB SSD (SLC) 128 GB SSD (MLC)	- RS-232C	NY532-5400-112213910 NY532-5400-112213K10

*1. The number of controlled axes of the MC Control Function Module is included.

*2. One CNC Operator License (SYSMAC-RTNC0001L) is attached with the CPU Unit.

Automation Software Sysmac Studio

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. Each model of licenses does not include any DVD.

Product name	Specifications	Number of licenses	Media	Model
Sysmac Studio Standard	The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/ NX-series CPU Units, NY-series Industrial PC, EtherCAT Slave, and the HMI. Sysmac Studio runs on the following OS. Windows 7 (32-bit/64-bit version)/Windows 8 (32-bit/64-bit version)/Windows 8.1 (32-bit/64-bit version)/Windows 8 (32-bit/64-bit version)/Windows 8.1 (32-bit/64-bit vers	_ (Media only)	DVD	SYSMAC-SE200D
Edition Ver.1.	version)/Windows 10 (32-bit/64-bit version) The Sysmac Studio Standard Edition DVD includes Support Software to set up EtherNet/IP Units, DeviceNet slaves, Serial Communications Units, and Support Software for creating screens on HMIs (CX-Designer). For details, refer to the Sysmac Integrated Catalogue (P072).	1 license *	_	SYSMAC-SE201L

*Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).

Collection of software functional components Sysmac Library

Please download it from following URL and install to Sysmac Studio.

http://www.ia.omron.com/sysmac_library/

Typical Models

Product	Product Features			
Vibration Suppression Library	The Vibration Suppression Library is used to suppress residual vibration caused by the operation of machines.	SYSMAC-XR006		
Device Operation Monitor Library	The Device Operation Monitor Library is used to monitor the operation of devices such as air cylinders, sensors, motors, and other devices.	SYSMAC-XR008		
Dimension Measurement Library	The Dimension Measurement Library is used to dimension measurement with ZW-7000/5000 Confocal Fiber Displacement Sensor, or E9NC-TA0 Contact-Type Smart Sensor.	SYSMAC-XR014		

Operation Software CNC Operator

Please purchase a DVD or download it from following URL.

http://www.ia.omron.com/cnc-operator/

One CNC Operator License (SYSMAC - RTNC0001L) is attached with the CPU Unit.

Product name	Specifications	Number of licenses	Media	Model	Standards
	The CNC Operator is the software that provides a operation interface for NC programming, debugging and maintenance of CNC machine.	 (Installer only)	 (Download)	SYSMAC-RTNC0000	
CNC Operator	CNC Operator runs on the following OS. Windows 7 (32-bit/64-bit version)/Windows 8 (32-bit/64-bit version)/Windows 8.1 (32-bit/64-bit version)/Windows 10 (32-bit/64-bit version)	 (Media only)	(Media only) DVD SYSMAC-RTNC0000D		
CNC Operator License	The one license key (hardware key, USB dongle). The CNC Operator needs license key.	1 license		SYSMAC-RTNC0001L	
CNC Operator Software Development Kit	The CNC Operator Software Development Kit provides a environment for customization of CNC Operator. Supported execution environment: .NET Framework (4.6.1) Development environment: Visual Studio 2013/2015 Development languages: C#		DVD	SYSMAC-RTNC0101D	

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Accessories

Optional Hardware

Product name	Specifications	Model
	Book mount	NY000-AB00
Iounting Brackets *1	Wall mount	NY000-AB01
SD Memory Cards	Card type: SD Card Capacity: 2 GB Format: FAT16	HMC-SD291
	Card type: SDHC Card Capacity: 4 GB Format: FAT32	HMC-SD491
ISB Flash Drives	Capacity: 2 GB	FZ-MEM2G
SD Hash Drives	Capacity: 8 GB	FZ-MEM8G
	Storage type: HDD Capacity: 320 GB	NY000-AH00
Storage Devices	Storage type: SSD SLC Capacity: 32 GB	NY000-AS00
Storage Devices	Storage type: SSD SLC Capacity: 64 GB	NY000-AS01
	Storage type: SSD MLC Capacity: 128 GB	NY000-AS02
USB Type-A to USB Type-B	Cable length: 2 m USB 2.0 Minimum bend radius: 25 mm	FH-VUAB 2M
Cables	Cable length: 5 m USB 2.0 Minimum bend radius: 25 mm	FH-VUAB 5M
DVI Cables	Cable length: 2 m Supports DVI-D Minimum bend radius: 36 mm	NY000-AC00 2M
JVI Cables	Cable length: 5 m Supports DVI-D Minimum bend radius: 36 mm	NY000-AC00 5M
ndustrial Monitor	 LCD touchscreen Multi-touch functionality Supply voltage: 24 VDC Up to 1,280 x 800 pixels at 60 Hz 2 USB Type-A Connectors Programmable brightness control Standard and 100 m cable models are available. 	NYM1□W-C10□□
Power Supply	Output voltage: 24 VDC Push-In Plus terminal blocks	S8VK-S0024
JPS * 2	Output voltage during backup operation: 24 VDC ± 5%	S8BA
JPS Communication Cable	Cable length: 2 m Signals for • Signal output (BL, TR, BU, WB) • Remote ON/OFF input • UPS Stop Signal input (BS)	S8BW-C02

*1. Select the required type. Industrial Box PC type only.*2. Revision number 04 or higher.

The revision number of the UPS can be retrieved from the serial number label on the product and the product packaging.

A30 00000000 00 0

1	2 3 4
Item	Description
1	Product code
2	Product period and sequential number
3	Revision number
4	RoHS status

Spare Parts

The following spare parts for the Industrial PC are available.

Product name	Specifications	Model
Battery	One battery is supplied with the Industrial PC. The battery supplies power to the real-time clock. The battery is located inside the Industrial PC. Service life: 5 years at 25°C	CJ1W-BAT01
Fan Unit	The Fan Unit is available for the Industrial PC that has active cooling. Service life: 70,000 hours of continuous operation at 40°C with 15% to 65% relative humidity. Shelf life: 6 months This is the storage limitation with no power supplied.	NY000-AF00
Accessory Kit	Replacement kit containing all accesories supplied with Industrial PC. • Power connector • //O connector • Drive bracket for drive installation • 4 mounting screws for drive installation • PCIe Card support for PCIe Card installation • PCIe Card clip for PCIe Card installation	NY000-AK00

Installed Support Software

Item	Specifications
Industrial PC Support Utility	The Industrial PC Support Utility is a software utility to assist in diagnosing and resolving problems of the Industrial PC.
	It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial PC Tray Utility	The Industrial PC Tray Utility is a software utility that provides information about the current state of the Industrial PC, its related devices, and associated software. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial PC System API	The Industrial PC System API allows programmers to create programs that can retrieve information or set an indicator status of the Industrial PC. The API makes use of the included IPC System Service to manage the hardware. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial Monitor Utility	The Industrial Monitor Utility provides a user interface to control settings and display details of connected Industrial Monitors. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial Monitor Brightness Utility	The Industrial Monitor Brightness Utility is a small software utility that allows you to control the brightness of the screen backlight of all connected Industrial Monitors. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial Monitor API	The Industrial Monitor API allows programmers to create applications that can control the hardware features and retrieve information from connected Industrial Monitors. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial PC Rescue Disk Creator	The Industrial PC Rescue Disk Creator creates a USB Rescue Disk which can be used to back-up and restore the Omron IPC Operating System. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.

Recommended EtherCAT and EtherNet/IP Communications Cables

Use a straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (aluminum tape and braiding) for EtherCAT. For EtherNet/IP, required specification for the communications cables varies depending on the baud rate.

For 100BASE-TX/10BASE-T, use a straight or cross STP (shielded twisted-pair) cable of category 5 or higher.

For 1000BASE-T, use a straight or cross STP cable of category 5e or higher with double shielding (aluminum tape and braiding).

Cabel with Connectors

Item	Appearance	Recommended manufacturer	Cable length (m)	Model
			0.3	XS6W-6LSZH8SS30CM-Y
Cable with Connectors on Both Ends (RJ45/RJ45)			0.5	XS6W-6LSZH8SS50CM-Y
Standard RJ45 plugs type *1 Wire Gauge and Number of Pairs: AWG26, 4-pair Cable		OMBON	1	XS6W-6LSZH8SS100CM-Y
Cable Sheath material: LSZH *2		OWRON	2	XS6W-6LSZH8SS200CM-Y
Cable color: Yellow *3			3	XS6W-6LSZH8SS300CM-Y
			5	XS6W-6LSZH8SS500CM-Y
			0.3	XS5W-T421-AMD-K
Cable with Connectors on Both Ends (RJ45/RJ45)		OMRON	0.5	XS5W-T421-BMD-K
Rugged RJ45 plugs type *1	*0*		1	XS5W-T421-CMD-K
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable			2	XS5W-T421-DMD-K
Cable color: Right blue			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
			0.5	XS5W-T421-BM2-SS
Cable with Connectors on Both Ends (M12 Straight/M12 Straight)			1	XS5W-T421-CM2-SS
Shield Strengthening Connector cable *4 M12/Smartclick Connectors		OMRON	2	XS5W-T421-DM2-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable	-0		3	XS5W-T421-EM2-SS
Cable color: Black			5	XS5W-T421-GM2-SS
			10	XS5W-T421-JM2-SS
		0 20	0.5	XS5W-T421-BMC-SS
Cable with Connectors on Both Ends (M12 Straight/RJ45) Shield Strengthening Connector cable *4	~ 0	- (52)	1	XS5W-T421-CMC-SS
M12/Smartclick Connectors	0.05	OMBON	2	XS5W-T421-DMC-SS
Rugged RJ45 plugs type	0	OMINON	3	XS5W-T421-EMC-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black	V M A 9		5	XS5W-T421-GMC-SS
			10	XS5W-T421-JMC-SS

*1. Cables with standard RJ45 plugs are available in the following lengths: 0.2 m, 0.3 m, 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m, 7.5 m, 10 m, 15 m, 20 m. Cables with rugged RJ45 plugs are available in the following lengths: 0.3 m, 0.5 m, 1 m, 2 m, 3 m, 5 m, 10 m, 15 m. For details, refer to the *Industrial Ethernet Connectors Catalog* (Cat. No. G019).

*2. The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PUR cables for out-of-cabinet use. Although the LSZH cable is single shielded, its communications and noise characteristics meet the standards.

*3. Cable colors are available in yellow, green, and blue.

***4.** For details, contact your OMRON representative.

Cables / Connectors

	Item	Recommended manufacturer	Model	
Products for EtherCAT or			Hitachi Metals, Ltd.	NETSTAR-C5E SAB 0.5 × 4P *1
EtherNet/IP (1000BASE-T/100BASE-TX)	Wire Gauge and Number of	Cables	Kuramo Electric Co.	KETH-SB *1
	Pairs: AWG24, 4-pair Cable		SWCC Showa Cable Systems Co.	FAE-5004 *1
		RJ45 Connectors	Panduit Corporation	MPS588-C *1
		Cables	Kuramo Electric Co.	KETH-PSB-OMR *2
		Cables	JMACS Japan Co., Ltd.	PNET/B *2
Products for EtherCAT or EtherNet/IP (100BASE-TX/10BASE-T)	Wire Gauge and Number of Pairs: AWG22, 2-pair Cable	RJ45 Assembly Connector	OMRON	XS6G-T421-1 *2

***1.** We recommend you to use above Cable, and RJ45 Connector together.

*2. We recommend you to use above Cable, and RJ45 Assembly Connector together.

Note: Connect both ends of cable shielded wires to the connector hoods.

Specifications

Performance Specifications Supported by NY5□□-1/NY5□□-5

				NY5□□-		
		Item		15	14□□/5400	13
Processing	g Instruction LD instruction			0.33 ns		
time execution times		Math instructions	(for Long Real Data)	1.2 ns or more		
		Size		40 MB		
	Program capacity *1	Normality	POU definition 3,000			
	*	Number	POU instance	24,000		
D		No retain	Size	64 MB		
Programming		attribute	Number	180,000		
	Variables capacity	Datain attailanta	Size	4 MB		
		Retain attribute	Number	40,000		
	Data type	Number	-	4,000		
Unit configuration	Maximum number of connectable units	Maximum numbe	r of NX unit on the system	4,096 (on NX series	EtherCAT slave termin	nal)
		Maximum number of controlled axes		The number of contr	f axes which can be de olled axes = The numb gle-axis position contro	er of motion control axes
	Number of controlled axes			64 axes	32 axes	16 axes
			Motion control axes		Maximum number of motion control axes which can be defined. A motion control function is available.	
				64 axes	32 axes	16 axes
		Maximum number of used real axes		Maximum number o The Number of used encoder axes.	f used real axes. d real axes includes fol	lowing servo axes and
Motion control			Used motion control servo axes	Maximum number of servo axes which all motion control functio available. The number of used motion control servo axes = The number or motion control axes whose axis type is set to servo axis and axis is set to used axis.		axes = The number of
			416	64 axes	32 axes	16 axes
		Maximum numbe axis control	r of axes for linear interpolation	4 axes per axes group		
		Number of axes for a	circular interpolation axis control	2 axes per axes group		
	Maximum number o	of axes groups	101 199	32 axes groups		
	Motion control perio	od C	I INE.	The same control period as that is used for the process data communications cycle for EtherCAT.		r the process data
		Number of cam	Maximum points per cam table	65,535 points		
	Cams	data points	Maximum points for all cam tables	1,048,560 points		
		Maximum numbe	r of cam tables	640 tables		
	Position units			Pulses, millimeters,	micrometers, nanomet	ers, degrees and inches
	Override factors			0.00% or 0.01% to 5	500.00%	

*1. This is the capacity for the execution objects and variable tables (including variable names).

NY500-1/NY500-5

					NY5□□-	
		Item	15□□	14□/5400	13□□	
	Number of port					
	Physical layer			10BASE-T/100BASE	E-TX/1000BASE-T	
	Frame length			1,514 max.		
	Media access meth	od		CSMA/CD		
	Modulation			Baseband		
	Topology			Star		
	Baud rate			1Gbps (1000BASE-1	Г)	
	Transmission medi	a		STP (shielded, twister	d-pair) cable of Ethernet cat	egory 5, 5e or higher
	Maximum transmis	sion distance betwe	en Ethernet switch and node	100 m	. ,	• • • •
	Maximum number o	of cascade connecti	ons	There are no restrict	ions if Ethernet switch is u	sed.
		Maximum number	r of connections	128		
		Packet interval *2	2	1 to 10,000 ms in 1.0 Can be set for each		
		Permissible com	nunications band * 3	20,000 pps including	heartbeat	
Built-in		Maximum number	r of tag sets	128		
EtherNet/IP Port		Tag types		Network variables		
Port	CIP service: Tag		r connection (i.e., per tag set)	8 (7 tags if Controlle	r status is included in the t	ag set.)
	data links (Cyclic communications)	Maximum link data size per node (total size for all tags)		184,832 byte		
		Maximum number of tag		256		
		Maximum data size per connection		1,444 bytes		
		Maximum number of registrable tag sets		128 (1 connection = 1 tag set)		
		Maximum tag set size		1,444 bytes (Two bytes are used if Controller status is included in the tag set		ided in the tag set.)
		Multi-cast packet filter *4		Supported.		
	Class 3 (number of con			64 (clients plus serve	er)	
	Cip Message Service: explicit messages	исмм	Maximum number of clients that can communicate at one time	32	.,	
		(non-connection type)	Maximum number of servers that can communicate at one time	32		
	Maximum number of TCP socket servi			30		
	Number of port			1		
	Communications st	andard	I I SIE	IEC 61158 Type12		
	EtherCAT master s	pecifications			ck Motion Control complia	nt)
	Physical layer	him	of P.	100BASE-TX		
	Modulation			Baseband		
	Baud rate		-	100 Mbps (100Base	-TX)	
	Duplex mode			Auto		
	Topology			Line, daisy chain, an	d branching	
Built-in	Transmission medi	a			f category 5 or higher aight cable with aluminum	tape and braiding)
EtherCAT port	Maximum transmis	sion distance betwe	en nodes	100 m		
	Maximum number o	of slaves		192		
	Range of node add	ress		1-512		
	Maximum process	data size		Inputs: 5,736 bytes Outputs: 5,736 bytes (However, the maxin	s num number of process da	ata frames is 4.)
	Maximum process	data size per slave		Inputs: 1,434 bytes Outputs: 1,434 bytes	· · ·	
	Communications c	/cle		500 µs to 8 ms (in 25		
	Sync jitter			1 μs max.	. ,	
Internal clock				At ambient temperat At ambient temperat	ure of 55°C: -3.5 to +0.5 n ure of 25°C: -1.5 to +1.5 n ure of 0°C: -3 to +1 min er	nin error per month

*2. Data will be refreshed at the set interval, regardless of the number of nodes.
*3. "pps" means packets per second, i.e., the number of communications packets that can be sent or received in one second.
*4. As the EtherNet/IP port implements the IGMP client, unnecessary multi-cast packets can be filtered by using a switching hub that supports IGMP Snooping.

Performance Specifications Supported by NY5□□-5

		Item		NY532-
		nem		5400
	Task period	Primary periodic cycle		500/1,000/2,000/4,000/8,000 μs
	lask periou	CNC Planner Service per	riod	500 μs to 16 ms
	Number of CNC motors	Maximum number of CN	C motors * 1	32
		Maximum number of CN	C coordinate systems	8
	CNC coordinate system	Maximum number of CNC motor configurations that are included in a CNC coordinate system (excluding spindle axes)		8
	-,	Number of spindle axes that are included in a CNC coordinate system		1
Numerical	Number of simultaneous interpolation axes			4
Control		Program buffer size *2		64 MB
	NC Program	NC Program Maximum number of programs	Upper limit of main registrations	512
			Upper limit of sub registrations	512
		P variable		Double-precision floating point 65536 *3
	NC program variables	Q variable		Double-precision floating point 8192 *3
		L variable		Double-precision floating point 256
	CNC motor	Maximum number of CN	C motor compensation tables	64
	compensation table	Maximum size of all com	pensation tables	2 MB

***1.** The number of controlled axes of the MC Control Function Module is included.

e smaller than th *2. The number of programs and their capacities that can be loaded into the CPU Unit at the same time. The program capacity is the maximum size available. As fragmentation will occur, the size that is actually available will be smaller than the maximum size.
*3. Some parts of the area are reserved by the system.

Function Specifications Supported by NY5□□-1/NY5□□-5

		Item		NY5□□-1/NY5□□-5
	Function			I/O refreshing and the user program are executed in units that are calle tasks. Tasks are used to specify execution conditions and execution priority.
Tasks		Periodically executed tasks	Maximum number of primary periodic tasks	1
		executed tasks	Maximum number of periodic tasks	3
			Maximum number of event tasks	32
		Conditionally executed tasks	Execution conditions	When Activate Event Task instruction is executed or when condition expression for variable is met.
		Programs	L	POUs that are assigned to tasks.
	POU (program	Function blocks		POUs that are used to create objects with specific conditions.
	organization units)	Functions		POUs that are used to create an object that determine unique outputs f the inputs, such as for data processing.
	Programming languages	Types		Ladder diagrams *1 and structured text (ST)
	Namespaces			A concept that is used to group identifiers for POU definitions.
	Variables	External access of variables	Network variables	The function which allows access from the HMI, host computers, or oth Controllers
			Boolean	BOOL
			Bit strings	BYTE, WORD, DWORD, LWORD
			Integers	INT, SINT, DINT,LINT, UINT, USINT, UDINT, ULINT
			Real numbers	REAL LREAL
		Basic data	Durations	TIME
		types	Dates	DATE
			Times of day	TIME_OF_DAY
			Date and time	DATE_AND_TIME
	Data types	Devivetive data t		STRING
			Text strings	
		Derivative data ty		Structures, unions, enumerations
Programming			Function	A derivative data type that groups together data with different variable types.
			Maximum number of members	2048
		Structures	Nesting maximum levels	8
			Member data types	Basic data types, structures, unions, enumerations, array variables
		ntil	Specifying member offsets	You can use member offsets to place structure members at any memo locations.
		Unions	Function	A derivative data type that groups together data with different variable types.
		Chiefie	Maximum number of members	4
			Member data types	BOOL, BYTE, WORD, DWORD, LWORD
		Enumerations	Function	A derivative data type that uses text strings called enumerators to exprevariable values.
		Array specifications	Function	An array is a group of elements with the same data type. You specify th number (subscript) of the element from the first element to specify the element.
	Data tana		Maximum number of dimensions	3
	Data type attributes	specifications	Maximum number of elements	65535
			Array specifications for FB instances	Supported.
		Range specificat	ions	You can specify a range for a data type in advance. The data type can take only values that are in the specified range.
	Libraries			User libraries
	Control modes			position control, velocity control, torque control
	Axis types			Servo axes, virtual servo axes, encoder axes, and virtual encoder axes
	Positions that c	an be managed		Command positions and actual positions
			Absolute positioning	Positioning is performed for a target position that is specified with an absolute value.
Motion	Single-axis	Single-axis	Relative positioning	Positioning is performed for a specified travel distance from the comman current position.
Motion control		position control	Interrupt feeding	Positioning is performed for a specified travel distance from the position where an interrupt input was received from an external input.
			Cyclic synchronous absolute positioning	A positioning command is output each control period in Position Contro Mode.
		Single-axis	Velocity control	Velocity control is performed in Position Control Mode.
		velocity control	Cyclic synchronous velocity control	A velocity command is output each control period in Velocity Control Mode.
		Single-axis torque control	Torque control	The torque of the motor is controlled.

***1.** Inline ST is supported. (Inline ST is ST that is written as an element in a ladder diagram.)

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		Item		NY5□□-1/NY5□□-5
			Starting cam operation	A cam motion is performed using the specified cam table.
			Ending cam operation	The cam motion for the axis that is specified with the input parameter is ended.
			Starting gear operation	A gear motion with the specified gear ratio is performed between a master axis and slave axis.
		Single-axis synchronized	Positioning gear operation	A gear motion with the specified gear ratio and sync position is performed between a master axis and slave axis.
		control	Ending gear operation	The specified gear motion or positioning gear motion is ended.
			Synchronous positioning	Positioning is performed in sync with a specified master axis.
			Master axis phase shift	The phase of a master axis in synchronized control is shifted.
			Combining axes	The command positions of two axes are added or subtracted and the result is output as the command position.
		Single-axis	Powering the servo	The Servo in the Servo Drive is turned ON to enable axis motion.
		manual operation	Jogging	An axis is jogged at a specified target velocity.
		•	Resetting axis errors	Axes errors are cleared.
			Homing	A motor is operated and the limit signals, home proximity signal, and home signal are used to define home.
			Homing with parameter	Specifying the parameter, a motor is operated and the limit signals, home proximity signal, and home signal are used to define home.
	Single-axis		High-speed homing	Positioning is performed for an absolute target position of 0 to return to home.
			Stopping	An axis is decelerated to a stop at the specified rate.
			Immediately stopping	An axis is stopped immediately.
			Setting override factors	The target velocity of an axis can be changed.
		Auxiliary	Changing the current position	The command current position or actual current position of an axis can be changed to any position.
		functions for	Enabling external latches	The position of an axis is recorded when a trigger occurs.
		single-axis	Disabling external latches	The current latch is disabled.
		control	Zone monitoring	You can monitor the command position or actual position of an axis to see when it is within a specified range (zone).
			Enabling digital cam switches	You can turn a digital output ON and OFF according to the position of an axis.
Motion			Monitoring axis following error	You can monitor whether the difference between the command positions or actual positions of two specified axes exceeds a threshold value.
control			Resetting the following error	The error between the command current position and actual current position is set to 0.
			Torque limit	The torque control function of the Servo Drive can be enabled or disabled and the torque limits can be set to control the output torque.
			Command position compensation	The function which compensate the position for the axis in operation.
			Start velocity	You can set the initial velocity when axis motion starts.
		h l'I	Absolute linear interpolation	Linear interpolation is performed to a specified absolute position.
		Multi-axes	Relative linear interpolation	Linear interpolation is performed to a specified relative position.
		coordinated	Circular 2D interpolation	Circular interpolation is performed for two axes.
			Axes group cyclic synchronous absolute positioning	A positioning command is output each control period in Position Control Mode.
			Resetting axes group errors	Axes group errors and axis errors are cleared.
			Enabling axes groups	Motion of an axes group is enabled.
	A		Disabling axes groups	Motion of an axes group is disabled.
	Axes groups		Stopping axes groups	All axes in interpolated motion are decelerated to a stop.
		Auxiliary functions for multi-axes	Immediately stopping axes groups	All axes in interpolated motion are stopped immediately.
		coordinated control	Setting axes group override factors	The blended target velocity is changed during interpolated motion.
			Reading axes group positions	The command current positions and actual current positions of an axes group can be read.
			Changing the axes in an axes group	The Composition Axes parameter in the axes group parameters can be overwritten temporarily.
			Setting cam table properties	The end point index of the cam table that is specified in the input parameter is changed.
		Cams	Saving cam tables	The cam table that is specified with the input parameter is saved in non- volatile memory in the CPU Unit.
	Common items		Generating cam tables	The cam table that is specified with the input parameter is generated from the cam property and cam node.
		Parameters	Writing MC settings	Some of the axis parameters or axes group parameters are overwritten temporarily.
			Changing axis parameters	You can access and change the axis parameters from the user program.

		Item		NY5□□-1/NY5□□-5	
		Count modes		You can select either Linear Mode (finite length) or Rotary Mode (infinite length).	
		Unit conversions		You can set the display unit for each axis according to the machine.	
		Acceleration/ deceleration	Automatic acceleration/ deceleration control	Jerk is set for the acceleration/deceleration curve for an axis motion or axes group motion.	
		control	Changing the acceleration and deceleration rates	You can change the acceleration or deceleration rate even during acceleration or deceleration.	
		In-position check	(You can set an in-position range and in-position check time to confirm when positioning is completed.	
		Stop method		You can set the stop method to the immediate stop input signal or limit input signal.	
		Re-execution of I	notion control instructions	You can change the input variables for a motion control instruction during execution and execute the instruction again to change the target values during operation.	
Motion	Auxiliary functions	Multi-execution of (Buffer mode)	of motion control instructions	You can specify when to start execution and how to connect the velocities between operations when another motion control instruction is executed during operation.	
control		Continuous axes (Transition mode		You can specify the Transition Mode for multi-execution of instructions for axes group operation.	
			Software limits	Software limits are set for each axis.	
			Following error	The error between the command current value and the actual current value is monitored for an axis.	
		Monitoring functions	Velocity, acceleration rate, deceleration rate, torque, interpolation velocity, interpolation acceleration rate, and interpolation deceleration rate	You can set and monitor warning values for each axis and each axes group.	
		Absolute encode	r support	You can use an OMRON 1S-series Servomotor or G5-Series Servomotor with an Absolute Encoder to eliminate the need to perform homing at startup.	
		Input signal logic	inversion	You can inverse the logic of immediate stop input signal, positive limit input signal, negative limit input signal, or home proximity input signal.	
	External interfac	e signals	The Servo Drive input signals listed on the right are used.	Home signal, home proximity signal, positive limit signal, negative limit signal, immediate stop signal, and interrupt input signal.	
Unit (I/O) management	EtherCAT slaves	Maximum numbe	er of slaves	192	
		Communications	protocol	TCP/IP, UDP/IP	
	Built-in EtherNet/IP port Internal Port	TCP/IP functions	CIDR	The function which performs IP address allocations without using a class (class A to C) of IP address.	
			IP Forwarding	The function which forward IP packets between interfaces.	
			Packet Filter #2	Check the IP packet, the function to determine whether to receive the source IP address and TCP port number.	
		- n1-1	NAT	Function for transfer by converting the two IP address.	
		CIP communications	Tag data links	Programless cyclic data exchange is performed with the devices on the EtherNet/IP network.	
		service	Message communications	CIP commands are sent to or received from the devices on the EtherNet/IP network.	
		тср/ір	Socket services	Data is sent to and received from any node on Ethernet using the UDP or TCP protocol. Socket communications instructions are used.	
			FTP client	File can be read from or written to computers at other Ethernet nodes from the CPU Unit. FTP client communications instructions are used.	
		applications	FTP server	Files can be read from or written to the SD Memory Card in the CPU Unit from computers at other Ethernet nodes.	
			SNMP agent	Built-in EtherNet/IP port internal status information is provided to network management software that uses an SNMP manager.	
Communications		Supported	Process data communications	A communications method to exchange control information in cyclic communications between the EtherCAT master and slaves. This communications method is defined by CoE.	
		services	SDO communications	A communications method to exchange control information in noncyclic event communications between EtherCAT master and slaves. This communications method is defined by CoE.	
		Network scannin	g	Information is read from connected slave devices and the slave configuration is automatically generated.	
	EtherCAT port	DC (distributed c	lock)	Time is synchronized by sharing the EtherCAT system time among all EtherCAT devices (including the master).	
		Packet monitorin	g	The frames that are sent by the master and the frames that are received by the master can be saved. The data that is saved can be viewed with WireShark or other applications.	
		Enable/disable se	ettings for slaves	The slaves can be enabled or disabled as communications targets.	
		Disconnecting/co	-	Temporarily disconnects a slave from the EtherCAT network for maintenance, such as for replacement of the slave, and then connects the slave again.	
		Supported application protocol	СоЕ	SDO messages of the CAN application can be sent to slaves via EtherCAT.	
	Communications	instructions		The following instructions are supported. CIP communications instructions, socket communications instructions, SDO message instructions, FTP client instructions, and Modbus RTU protcol instructions.	

***2.** Internal Port only.

		Item		NY5□□-1/NY5□□-5	
		Function		Events are recorded in the logs.	
System	Event logs	Maximum System event log		2,048	
management	Event logs	number of	Access event log	1,024	
		events	User-defined event log	1,024	
	Online editing	Single		Programs, function blocks, functions, and global variables can be changed online. Different operators can change different POUs across a network.	
	Forced refreshin	g		The user can force specific variables to TRUE or FALSE.	
		Maximum number of forced variables	Device variables for EtherCAT slaves	64	
	MC test run	1		Motor operation and wiring can be checked from the Sysmac Studio.	
	Synchronizing			The project file in the Sysmac Studio and the data in the CPU Unit can be made the same when online.	
	Differentiation m	onitoring		Rising/falling edge of contacts can be monitored.	
		Maximum numbe	er of contacts	8	
		Types	Single triggered trace	When the trigger condition is met, the specified number of samples are taken and then tracing stops automatically.	
Debugging		Types	Continuous trace	Data tracing is executed continuously and the trace data is collected by the Sysmac Studio.	
			er of simultaneous data trace	4	
		Maximum numbe		10,000	
		Sampling	Maximum number of sampled variables	192 variables	
	Data tracing	Timing of sampli	•	Sampling is performed for the specified task period, at the specified time, or when a sampling instruction is executed.	
		Triggered traces		Trigger conditions are set to record data before and after an event.	
			Trigger conditions	When BOOL variable changes to TRUE or FALSE Comparison of non- BOOL variable with a constant Comparison Method: Equals (=), Greater than (>), Greater than or equals (\geq), Less Than (<), Less than or equals (\leq), Not equal (\neq)	
			Delay	Trigger position setting: A slider is used to set the percentage of sampling before and after the trigger condition is met.	
	Simulation			The operation of the CPU Unit is emulated in the Sysmac Studio.	
Poliobility		Controller errors	Levels	Major fault, partial fault, minor fault, observation, and information	
Reliability functions	Self-diagnosis	User-defined erro	ors	User-defined errors are registered in advance and then records are created by executing instructions.	
			Levels	8 levels	
	Protecting software assets and preventing	CPU unit names	and serial IDs	When going online to a CPU Unit from the Sysmac Studio, the CPU Unit name in the project is compared to the name of the CPU Unit being connected to.	
		oftware assets nd preventing	User program transfer with no restoration information	You can prevent reading data in the CPU Unit from the Sysmac Studio.	
			CPU unit write protection	You can prevent writing data to the CPU Unit from the Sysmac Studio or SD Memory Card.	
Security			Overall project file protection	You can use passwords to protect .smc files from unauthorized opening on the Sysmac Studio.	
	operating mistakes		Data protection	You can use passwords to protect POUs on the Sysmac Studio.	
		Verification of op	peration authority	Online operations can be restricted by operation rights to prevent damage to equipment or injuries that may be caused by operating mistakes.	
			Number of groups	5	
		Verification of user program execution ID		The user program cannot be executed without entering a user program execution ID from the Sysmac Studio for the specific hardware (CPU Unit).	
	Location to store)		Shared folder: The folder that exist on the HDD / SDD that Windows is running.	
Memory card		Memory card ope	eration instructions	You can access Memory Cards from instructions in the user program.	
functions	Application	File operations from the Sysmac Studio		You can perform file operations for Controller files in the Memory Card and read/write general-purpose document files on the computer.	
		File operations fr	rom FTP Client/Server	You can store and read files by the FTP client function and FTP server function.	
			Using system-defined variables	You can use system-defined variables to backup or compare data.	
Backup	SD memory card backup	Operation	Memory card operations dialog box on Sysmac Studio	Backup and verification operations can be performed from the SD Memory Card Operations Dialog Box on the Sysmac Studio.	
Backup functions	functions		Using instruction	Backup operation can be performed by using instruction.	
		Protection	Prohibiting backing up data to the SD memory card	Prohibit SD Memory Card backup functions.	
	Sysmac Studio c	ontroller backup f	unctions	Backup, restore, and verification operations for Units can be performed from the Sysmac Studio.	

Functions Supported by NY5-5 Besides functions of the NY5-1, functions supported by the NY5-5 are as follows.

		Ite	em		NY532-
					5400
		Axes types			Positioning axis, Spindle axis
		Control modes	des Positioning axis		Position control
			Spindle axis		Velocity control
		Positions that can	be managed		Absolute position (command), absolute position (actual), program position, remaining travel distance.
			Execute		Executes the NC program.
			Reset		Interrupt NC program.
			Single step exec	ution	Executes the NC program by block.
			Back trace	ution	Executes back trace of interpolation pass.
			Feed hold / Feed	hold reset	Temporarily stops the NC program, and restarts it.
		NC program	Optional stop	noiu reset	Stops the NC program with optional signal.
		execution	Optional block st	ton	Skips one block of the NC program with optional signal.
			Dry run	юр	Runs operation from the NC program.
			Machine lock		
					Locks each axis operation during execution of the NC program.
			Auxiliary lock		Locks M code output.
			Override	Denid Desiliening	Overrides the feed rate and spindle velocity.
				Rapid Positioning	Rapid feed of each CNC motor according to the motor setting.
			Position control	Linear interpolation	Interpolates linearly.
				Circular interpolation	Interpolates circularly, helically, spirally, or conically.
				Skip function	Rapid feed until an external signal is input.
			Return to referen	•	Returns to a specified position on the machine.
			Canned cycle	Rigid tap	Performs tapping machining.
		ordinate G Code	Feed function	Exact stop	Temporarily prevents blending of positioning operations before and after an exact stop direction.
				Exact stop mode	Mode in which anteroposterior positioning operations are not blended.
				Continuous-path mode	Mode in which anteroposterior positioning operations are blende
				Dwell	Waits for the specified period of time.
Numerical CNC			No	Machine Coordinate System	The coordinate system uses the machine home position as the home of the system.
ontrol	coordinate system		Coordinate system selection	Work Coordinate System	The coordinate system has work offset for the Machine Coordinate System.
			19 1	Local Coordinate System	The coordinate system has additional offset for the Work Coordinate System.
			Auxiliary for coordinate system	Absolute/relative selection	Specifies manipulated variable absolutely, or switches to the relative setting.
				Metric/inch selection	Selects metric or inch as the orthogonal axes unit system.
				Scaling	Scales the current coordinates of the orthogonal axes.
				Mirroring	Mirrors the current coordinates for the specified orthogonal axe
				Rotation	Rotate the current coordinates around the coordinates of the specified axis.
				Cutter compensation	Compensation of the tool edge path according to the tool radiu
			Tool functions	Tool length	Compensation of tool center point path according to the tool radiu
				compensation	length.
			M code/M code r	eset	Outputs M codes, and interlocks with sequence control programusing reset.
				CW/CCW/Stop	Outputs/stops velocity commands in velocity loop control mode
		M code	Spindle axis	Orientation	Stops spindle axis to the specified phase by setting up feed bar
				Offentation	loop.
			Subroutine call		Calls a subroutine of the NC program.
			Arithmetic opera	tion	Performs a calculation in the NC program.
			Branch control		Branches on condition in the NC program.
		NC programming	User variables		Memory area in the NC program used for processing such as da calculation.
		no programming		P variable	System global memory area common to CNC coordinate system
				Q variable	Global system area unique to each CNC coordinate system.
				L variable	Memory area that can be used as the primary area during execution of the NC program.
		Auxiliary control	Error reset		Function that resets errors or CNC coordinate system and CNC motor.
		functions	Immediate ator		Function that stops all the CNC motors of the CNC coordinate
		Immediate stop		system.	

NY500-1/NY500-5

					NY532-	
		Ite	m		5400	
		Positions that can be managed			Commanded positions and actual positions.	
			Absolute posit	tioning	Positioning is performed for a target position that is specified using an absolute value.	
		Position control	Relative positi	oning	Positioning is performed for a specified travel distance from the command current position.	
			Cyclic position	ning	A commanded position is output at each control period in Position Control Mode.	
		Spindle control	CW/CCW/Stop		Outputs/stops velocity commands in velocity loop control mode.	
		Manual operation	Powering the S	Servo	The Servo in the servo driver is turned ON to enable CNC motor operation.	
			Jogging		A CNC motor is jogged at a specified target velocity.	
		Auxiliary control functions	Homing		A CNC motor is operated, and the limit signals, home proximity signal, and home signal are used to define home.	
		Tunctions	Immediate stop		A CNC motor is stopped immediately.	
		CNC motor	Ball screw compensation		Pitch error compensation for one-dimensional ball screw.	
		compensation table	Cross-axis compensation		Compensation of one-dimensional cross-axis.	
		Auxiliary control functions	Homing		A CNC motor is operated, and the limit signals, home proximity signal, and home signal are used to define home.	
Numerical	CNC motor	Tunctions	Immediate sto	p	A CNC motor is stopped immediately.	
Control		CNC motor compensation table	Ball screw compensation		Pitch error compensation for one-dimensional ball screw.	
			Cross-axis compensation		Compensation of one-dimensional cross-axis.	
			Editing the CNC motor compensation table		Edit using sequence control program (Read/write).	
			In-position check		You can set an in-position range and in-position check time to confirm when positioning is completed.	
			Stop method		You can set the stop method to the immediate stop input signal or limit input signal.	
			Manita dia a	Software limits	Monitors the movement range of a CNC motor.	
		Auxiliary functions	Monitoring functions	Following error	Monitors the error between the command current value and the actual current value for a CNC motor.	
			Absolute encoder support		You can use an OMRON 1S-series Servomotor or G5-series Servomotor with an Absolute Encoder to eliminate the need to perform homing at startup.	
			Input signal logic inversion		You can inverse the logic of immediate stop input signal, positive limit input signal, negative limit input signal, or home proximity input signal.	
		External interface	External interface signals		The Servo Drive input signals listed on the right are used. Home signal, home proximity signal, positive limit signal, negative limit signal, immediate stop signal, and interrupt input signal.	
	Common items	Parameters	Changing CNC motor paramet	coordinate system and CNC ters	You can access and change the CNC coordinate system and CNC motor parameters from the user program.	

Performance Specifications

	Iter	n		NY5□□-1/NY5□□-5		
		CPU type		Intel [®] Core™ i7-4700EQ		
		Cores / Threa	ds	4/8		
	0.001	CPU base free	quency	2.4 GHz		
	CPU	Maximum tur	bo frequency	3.4 GHz		
		Cache		6 MB		
		Cooling detai	ls	Requires active cooling (fan)		
Main system		Memory size		8 GB		
Main System	Memory	Memory type		DDR3L (non ECC)		
	Trusted platfor	m module (TPM)	 Ensure the integrity of the platform Disk encryption Password protection and other uses of encryption 		
	Graphics contr	oller		Intel [®] HD Graphics. Up to two independent screens.		
				Intel [®] HD Graphics 4600		
	Watchdog			Yes		
Operating system	Windows OS			Windows Embedded Standard 7 - 32 bit *1 Windows Embedded Standard 7 - 64 bit		
		Hard disk driv	/e	• 320 GB • Serial ATA 3.0		
Storage devices	Drives	Solid state	SLC type	32 GB and 64 GB Serial ATA 3.1		
		drive	MLC type	• 128 GB • Serial ATA 3.1		
	Drive bay (HDD/SSD) *2		I	2		
	Power connect	or		• 24 VDC		
	I/O connector			2 inputs (Power ON/OFF Input and UPS Mode Input) and 1 output (Power Status Output		
	Number of ports		orts	2		
	USB 2.0 Type-A Ma USB 3.0 Type-A Ma	Maximum current		500 mA		
		Maximum cable length		5 m		
		Number of po	-	2		
Connectors		Maximum current		900 mA		
		Maximum cable length		3 m		
	Ethernet	Number of available ports		3		
	connectors Physical layer			10BASE-T, 100BASE-TX or 1000BASE-T		
		Video interface		Digital or analog		
	DVI-I	Besolution		Up to 1,920 x 1,200 pixels at 60 Hz		
	connector			Dependent upon connected monitor type and resolution		
	RS-232C		. casie iongui	Standard SUBD9 connector (Non-Isolated)		
		Video interfac	` A			
	DVI-D	Resolution		Digital only Up to 1.920 x 1.200 pixels at 60 Hz		
	2110	Maximum DV	cable length	Dependent upon connected monitor type and resolution		
Optional		Video interfac		Digital only		
connector (select		Resolution		1,280 x 800 pixels at 60 Hz		
one per system)	NY Monitor		10	RJ45		
	Link	Connector typ Cable shieldin max. length		S/FTP, Cat.6A, 100 m		
		USB data thro	oughput	280 Mbps max.		
	Configuration		- Jupat	X4 (4 lanes) up to Gen 3		
PCIe Card Slot	Card height			Standard height cards, 4.20 inches (106.7 mm) *3		
	Card length			Half length cards, 6.6 inches (167.65 mm)		
	Model			CJ1W-BAT01		
Battery	Service life			5 years at 25°C		
Fan unit	Model Service life			NY000-AF00 70,000 hours of continuous operation at 40°C with 15% to 65% relative humidity		
LED	cervice me			PWR, ERR, HDD, RUN		
			sales representa			

*1. For the 32 bit version, consult your OMRON sales representative.
*2. Depending on the model one or two drives are supported.
*3. Low profile cards, 2.536 inches (64.4 mm) are not supported.

Display Specifications

		lto m	Spec	ifications		
	Item		12.1 Inch models	15.4 Inch models		
		Display device	TFT LCD	TFT LCD		
		Screen size	12.1 inches	15.4 inches		
		Surface treatment	Anti glare treatment	-		
		Surface hardness	Mohs scale: 5 - 6			
	Display panel	Resolution	1,280 × 800 pixels at 60 Hz (horizontal × v	ertical)		
	*1	Colors	16,770,000 colors			
		Effective display area	261×163 mm (horizontal \times vertical)	331×207 mm (horizontal × vertical)		
lanlar		View angles	Left: 60°, Right: 60°, Top: 60°, Bottom: 60°			
isplay		Life	50,000 hours min. *2			
		Brightness adjustment	200 levels *3			
		Technology	Projected capacitive			
		Touch resolution	Touch accuracy 1.5% (4-5 mm)			
	Touch	Multitouch	Up to 5 simultaneous touches			
	TOUCH	Features	Water detection *4, hand palm rejection *	5, gloves * 6		
		Life	50,000,000 operations min.			
		EMC	Correct touchscreen operation is possible	within allowable EMC immunity conditions		

Note: Industrial Panel PC type only.

***1.** There may be some defective pixels in the display. This is not a fault as long as the numbers of defective light and dark pixels fall within the following standard range: light and dark pixels 10 or less. (There must not be 3 consecutive light/dark pixels.)

*2. This is the estimated time before brightness is reduced by half at room temperature and humidity.

The life expectancy is drastically shortened if used at high temperatures.

*3. If the brightness is set to very dark, it causes flickering or the screen will be too dark to use.

***4.** If water is detected the touch functionality will not be available.

***5.** If a palm is detected that specific area is neglected.

***6.** The touchscreen can be operated when wearing gloves. Check correct usage of the gloves before using them.

Electrical Specifications

	Item		NY51 Industrial Box PC type	NY53□ Industrial Panel PC type	
Rated power supply volt	age		24 VDC, non-isolated	1	
Allowable power supply	voltage range	, int	20.4 to 28.8 VDC		
Grounding method			Ground to less than 100 Ω		
Inrush current			At 24 VDC: 12 A / 6 ms max. for cold start at	room temperature	
Overvoltage category		1111111	JIS B3502 and IEC 61131-2: Category II		
EMC immunity level			IEC 61131-2: Zone B		
RTC accuracy		Ho	At ambient temperature of 55° C: -3.5 to +0.5 min error per month At ambient temperature of 25° C: -1.5 to +1.5 min error per month At ambient temperature of 0°C: -3 to +1 min error per month		
Power button life			100,000 operations		
Battery life			5 years at 25°C (for battery CJ1W-BAT01)		
Fan life			8 years of continuous operation at 40°C		
		wer consumption ves and expansions	114 W	132 W	
	Maximum power consumption excluding drives and expansions		81 W	99 W	
		HDD 320 GB	2 W		
Power consumption *	Drives	SSD SLC 32 GB	2 W		
	Drives	SSD SLC 64 GB	2 W		
		SSD MLC 128 GB	2 W		
	Expensione	USB	14 W max. ((2 x 500 mA at 5 V) + (2 x 900 mA at 5 V))		
	Expansions	PCle	15 W max.		

Note: Refer to the NY-series IPC Machine Controller Industrial Panel PC Hardware User's Manual (W557) or the NY-series IPC Machine Controller Industrial Box PC Hardware User's Manual (W556) for detail.

* The total power consumption is the sum of the power consumption of all items that are installed in your Industrial PC.

To guarantee S8BA UPS operation in combination with our IPC, the specified combination of UPS and power-supply must be used.

The required supply specifications for an Industrial Box PC.

Item	Minimum power requirements
Power supply	240 W
UPS	120 W

The required supply specifications for an Industrial Panel PC.

Item	Minimum power requirements
Power supply	240 W
UPS	240 W

Environmental Specifications

Item		Specifications		
		Industrial Box PC	Industrial Panel PC	
	Ambient operating temperature *1	0 to 55°C		
	Ambient storage temperature *1	-20 to 70°C		
	Ambient operating humidity *1	10% to 90% with no condensation		
	Ambient storage humidity *1 10% to 90% with no condensation			
	Operating atmosphere	No corrosive gases		
	Altitude	2,000 m max.		
	Noise resistance (during operation)	Conforms to IEC61000-4-4, 2 kV (power lines)		
Operation environment Vibration resistance (during operation)		 Conforms to IEC 60068-2-6. For a Box PC with an SSD: 5 to 8.4 Hz with 3.5 mm single amplitude and 8.4 to 150 Hz with 9.8 m/s² for 10 times each in X, Y and Z directions. For a Box PC with a HDD the vibration resistance depends on the mounting orientation *2. 	 The vibration resistance depends on the storage device(s): For a Panel PC with only SSD storage devices: 5 to 8.4Hz with 3.5 mm single amplitude and 8.4 to 150 Hz with 9.8 m/s² for 10 times each in X, Y and Z directions. Conforms to IEC 60068-2-6. For a Panel PC with one or more HDD storage devices the Panel PC must be installed in a vibration free environment. *3 	
Shock resistance (during operation)		Conforms to IEC 60068-2-27. 147 m/s ² , 3 times in each X, Y and Z directions	·	
	Installation method	Book mount, Wall mount	Mount on panel	
1	Degree of protection *4	_	Front of Monitor: IP65	
	Pollution degree	2 or less: Conforms to JIS B3502 and IEC 61131-2.		
Applicable sta	indards *5	EU Directives: EMC Directive 2014/30/EU (EN 61131 KC Registration, RCM, cULus	-2) and RoHS Directive	

***1.** The allowed ambient operating temperature and ambient humidity depend on product type, CPU type, mounting orientation, and storage device type. ***2.** Vibration resistance depends on the Box PC's mounting orientation and storage device type.

Mounting Orientation	SSD	HDD
Book	9.8 m/s²	2.5 m/s ²
Wall	9.0 11/5	4.9 m/s ²

***3.** A Panel PC with one or more HDD storage devices should not be used in applications subject to vibration.

Examples of applications subject to vibration:
AGV (Automated Guided Vehicles)

Tableting machine

Rail vehicle

Connector pin assembling machineBending machine

- Stacker crane
- Elevator

Ensure your Panel PC with HDD does not vibrate. When in doubt use a Panel PC with SSD storage devices.

***4.** The Panel PC may not operate properly in locations subjected to oil splashes for extended periods of time. (Industrial Panel PC type only) ***5.** Refer to the OMRON website (www.ia.omron.com) or contact your OMRON representative for the most recent applicable standards for each model.

Storage Device Specifications

Item	Specifications			
Model	NY000-AS00 NY000-AS01		NY000-AS02	NY000-AH00 *1
Capacity	32 GB	64 GB	128 GB	320 GB
Туре	SSD (SLC)		SSD (MLC)	HDD
S.M.A.R.T. support	Yes			·
Rotation speed		-		5,400 r/min
Interface	Serial ATA 3.1			Serial ATA 3.0
Sustained standard read speed	Up to 160 MB/s		Up to 430 MB/s	-
Sustained standard write speed	Up to 150 MB/s	Up to 150 MB/s Up to 190 MB/s		
Operating temperature	0 to 70°C			5 to 55°C
Operating humidity	10% to 95% (with no condensation)			 10% to 95% (with no condensation) 29°C wet-bulb temperature max.
Storage temperature	-40 to 100°C			-40 to 65°C
Storage humidity	10% to 95% (with no condensation)			 8% to 90% (with no condensation) 40°C wet-bulb temperature max.
Life	1,500 TB written / 11 years at a daily workload of 350 GB	3,000 TB written / 23 years at a daily workload of 350 GB	114 TB written / 3 years at a daily workload of 100 GB	Approximately 5 years or 20,000 powered-ON hours (whichever comes first) under the following conditions: • 25°C at 101.3 kPa • Less than 333 powered-ON hours/ month *2 • Less than 20% operation while powered-ON *3 • Less than 1.30 x 10 ⁶ seeks/month

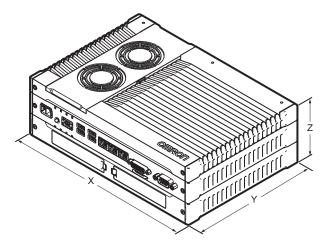
*1. For a Panel PC with an HDD: this device can only be installed in a vibration free environment only.

*2. Powered-ON hours include sleep and standby modes.

***3.** Operation includes seeking, writing, and reading functions.

Dimensions

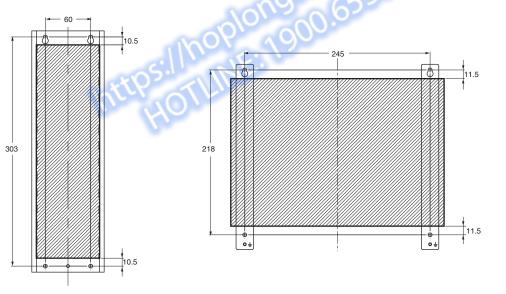
Industrial Box PC type



Item Specifications	
Dimensions	Width X = 282 mm Depth Y = 195 mm. Y = 200 mm including the DVI connectors. Height Z = 88.75 mm
Weight	3.8 kg

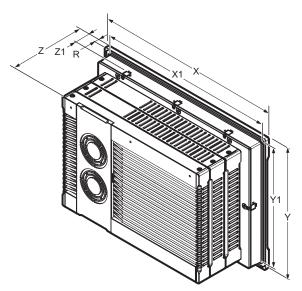
Bracket Specifications

The metal mounting brackets mount your Industrial Box PC and they are the connection for the functional ground. Use metal screws with a diameter of 4 mm or 5 mm to mount the brackets. Mounting screw locations for book mount and wall mount orientation:



(Unit: mm)

Industrial Panel PC type



Item	Specifications		
item	12.1 Inch	15.4 Inch	
Panel cutout dimensions	Cutout Width X1 = 314^{-0+1} mm Cutout Height Y1 = 216^{-0+1} mm	Cutout Width X1 = 383^{-0+1} mm Cutout Height Y1 = 259^{-0+1} mm	
Panel thickness range *	Panel thickness range Z1 = 1.6 to 6.0 mm	Panel thickness range Z1 = 1.6 to 6.0 mm	
Dimensions	Width X = 332 mm Height Y = 234 mm Depth Z = 121 mm	Width X = 401 mm Height Y = 277 mm Depth Z = 121 mm	
Monitor thickness in front of panel	Rim thickness R = 8.0 mm		
Weight	6.1 kg	7.2 kg	
* The minimum panel thickness depends on the panel material.			

Version Information

Unit Versions

Units	Models	Unit Version
IPC Machine Controller	NY5□2-1	Unit version 1.14
		Unit version 1.12
NC Integrated Controller	NY500-5	Unit version 1.16

Unit Versions and Programming Devices Supported by NY500-1/NY500-5

The following tables show the relationship between unit versions and Sysmac Studio versions. **Unit Versions and Programming Devices**

Unit Version *	Corresponding version of Sysmac Studio
1.16	1.20
1.14	1.19
1.14	1.18
1.12	1.17

* There is no NY50-1 with unit version 1.11 or earlier. There is no NY50-5 with unit version 1.16 or earlier.
Note: If you use a lower version of the Sysmac Studio, you can use only the functions of the unit version of the unit that corresponds to the Sysmac Studio version.

If you use a unit with an earlier version, select the unit version of the connected unit or an earlier unit version in the Select Device Area of the Project Properties Dialog Box on the Sysmac Studio. You can use only the functions that are supported by the unit version of the connected unit.

Unit Versions, CNC Versions and Programming Devices Supported by NY500-5 (NY-series NC Integrated Controller)

Unit Version	CNC Version	Corresponding version of Sysmac Studio	
Ver.1.16	Ver.1.00	Ver.1.20	
Note: If you use a lower version of the Sysmac Studio, you can use only the functions of the unit version of the CPU Unit that corresponds to the			

Sysmac Studio version. If you use a CPU Unit with an earlier version, select the unit version of the connected CPU Unit or an earlier unit version in the Select Device Area of the Project Properties Dialog Box on the Sysmac Studio. You can use only the functions that are supported by the unit version of the connected CPU Unit.



Related Manuals

Refer to the Related Manuals in the data sheet of the NY-series Industrial Box PC or NY-series Industrial Panel PC for the Related Manuals.

Manual name	Cat. No.	Model numbers	Application	Description
NY-series IPC Machine Controller Industrial Panel PC Hardware User's Manual	W557	NY532-000	Learning the basic specifications of the NY-series Industrial Panel PCs, including introductory information, designing, installation, and maintenance. Mainly hardware information is provided.	An introduction to the entire NY-series system is provided along with the following information on the Industrial Panel PC. • Features and system configuration • Introduction • Part names and functions • General specifications • Installation and wiring • Maintenance and inspection
NY-series IPC Machine Controller Industrial Box PC Hardware User's Manual	W556	NY512	Learning the basic specifications of the NY-series Industrial Box PCs, including introductory information, designing, installation, and maintenance. Mainly hardware information is provided.	An introduction to the entire NY-series system is provided along with the following information on the Industrial Box PC. • Features and system configuration • Introduction • Part names and functions • General specifications • Installation and wiring • Maintenance and inspection
NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Setup User's Manual	W568	NY532 NY512	Learning the initial settings of the NY-series Industrial PCs and preparations to use Controllers.	The following information is provided on an introduction to the entire NY-series system. • Two OS systems • Initial settings • Industrial PC Support Utility • NYCompolet • Industrial PC API • Backup and recovery
NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Software User's Manual	W558	NY532 NY512	Learning how to program and set up the Controller functions of an NY- series Industrial PC.	The following information is provided on NY-series Machine Automation Control Software. • Controller operation • Controller features • Controller settings • Programming based on IEC 61131-3 language specifications
NY-series Instructions Reference Manual	W560	NY532-000 NY512-000	Learning detailed specifications on the basic instructions of an NY- series Industrial PC.	The instructions in the instruction set (IEC 61131-3 specifications) are described.
NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Motion Control User's Manual	W559	NY532 NY512	Learning about motion control settings and programming concepts of an NY-series Industrial PC.	The settings and operation of the Controller and programming concepts for motion control are described.
NY-series Motion Control Instructions Reference Manual	W561	NY532-000 NY512-000	Learning about the specifications of the motion control instructions of an NY-series Industrial PC.	The motion control instructions are described.
NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Built-in EtherCAT [®] Port User's Manual	W562	NY532-	Using the built-in EtherCAT port in an NY-series Industrial PC	Information on the built-in EtherCAT port is provided. This manual provides an introduction and provides information on the configuration, features, and setup.
NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Built-in EtherNet/IP [™] Port User's Manual	W563	NY532 NY512	Using the built-in EtherNet/ IP port in an NY-series Industrial PC.	Information on the built-in EtherNet/IP port is provided. Information is provided on the basic setup, tag data links, and other features.
NY-series Troubleshooting Manual	W564	NY532-000 NY512-000	Learning about the errors that may be detected in an NY-series Industrial PC.	Concepts on managing errors that may be detected in an NY-series Controller and information on individual errors are described.
NJ/NY-Series NC Integrated Controller User's Manual	O0300-E1	NJ501-5300 NY532-5400	For numerical control with NJ/NY- series	Describes the numerical control function. When programming, use this manual together with the G Code Instructions Reference Manual (O0301-E1).
NJ/NY-Series NC Integrated Controller Instruction Reference Manual G code	O0301-E1	NJ501-5300 NY532-5400	Learning about detailed specifications of the G code/M code instructions.	This section describes G code/M code instructions in detail. When programming, use this manual together with the User's Manual (O0301-E1).
CNC Operator Operation Manual	O0302-E1	SYSMAC- RTNC0□□□D	Learning the overview of CNC Operator and how to use it.	Describes the CNC Operator, installation procedure, basic operation, connection operation, and operating procedures for main functions.
Sysmac Studio Version 1 Operation Manual	W504	SYSMAC-SE2	Learning about the operating procedures and functions of the Sysmac Studio.	Describes the operating procedures of the Sysmac Studio.
UPS S8BA User's Manual	U702	S8BA	Learning the information that is necessary to use the Uninterruptible Power Supply (UPS) Unit.	An introduction to the UPS is provided along with the following information: • Overview • Preparation • Installation and Connection • Check and Start Operation • Maintenance and Inspection • Shutdown Processing • I/O Signal Functions • Troubleshooting

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